

The metric in the superspace of Riemannian metrics and its relation to gravity*

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Abstract

The space of all Riemannian metrics is infinite-dimensional. Nevertheless a great deal of usual Riemannian geometry can be carried over. The superspace of all Riemannian metrics shall be endowed with a class of Riemannian metrics; their curvature and invariance properties are discussed. Just one of this class has the property to bring the lagrangian of General Relativity into the form of a classical particle's motion. The signature of the superspace metric depends in a non-trivial manner on the signature of the original metric, we derive the corresponding formula. Our approach is a local one: the essence is a metric in the space of all symmetric rank-two tensors, and then the space becomes a warped product of the real line with an Einstein space.

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1 THE SUPERSPACE

Let $n \geq 2$, n be the dimension of the basic Riemannian spaces. Let M be an n -dimensional differentiable manifold with an atlas x of coordinates x^i , $i = 1, \dots, n$. The signature s (= number of negative eigenvalues) shall be fixed; let V be the space of all Riemannian metrics $g_{ij}(x)$ in M with signature s , related to the coordinates x^i . This implies that isometrical metrics in M are different points in V in general. The V is called superspace, its points are the Riemannian metrics. The tangent space in V is the vector space

$$T = \{h_{ij}(x) | x \in M, h_{ij} = h_{ji}\} \quad (1)$$

the space of all symmetric tensor fields of rank 2. All considerations are local ones, so we may have in mind one single fixed coordinate system in M .

2 COORDINATES IN SUPERSPACE

Coordinates should possess one contravariant index, so we need a transformation of the type

$$y^A = \mu^{Aij} g_{ij}(x) \quad (2)$$

such that the y^A are the coordinates for V . To have a defined one-to-one correspondence between the index pairs (i, j) and the index A we require

$$A = 1, \dots, N = n(n+1)/2,$$

and $A = 1, \dots, N$ corresponds to the pairs

$$\begin{aligned} (1, 1), (2, 2), \dots, (n, n), (1, 2), (2, 3), \dots, (n-1, n), (1, 3), \\ \dots, (n-2, n), \dots, (1, n) \end{aligned} \quad (3)$$

consecutively. (i, j) and (j, i) correspond to the same A . We make the ansatz

$$\begin{aligned} \mu^{Aij} = \mu_{Aij} = b \text{ for } i \neq j, \quad c \text{ for } i = j \\ 0 \text{ if } (i, j) \text{ does not correspond to } A \end{aligned} \quad (4)$$

and require the usual inversion relations

$$\mu^{Aij} \mu_{Bij} = \delta_B^A \quad \text{and} \quad \mu^{Aij} \mu_{Akl} = \delta_k^{(i} \delta_l^{j)}. \quad (5)$$

Bracketed indices are to be symmetrized, which is necessary because of symmetry of the metric g_{ij} . Inserting ansatz (4) into (5) gives $c^2 = 1$, $b^2 = 1/2$. Changing the sign of b or c only changes the sign of the coordinates, so we may put

$$c = 1, \quad b = 1/\sqrt{2}. \quad (6)$$

The object μ^{Aij} is analogous to the Pauli spin matrices relating two spinorial indices to one vector index.

3 METRIC IN SUPERSPACE

The metric in the superspace shall be denoted by H_{AB} , it holds

$$H_{AB} = H_{BA} \quad (7)$$

and the transformed metric is

$$G^{ijkl} = H_{AB} \mu^{Aij} \mu^{Bkl}, \quad H_{AB} = \mu_{Aij} \mu_{Bkl} G^{ijkl}. \quad (8)$$

From (4) and (7) it follows that

$$G^{ijkl} = G^{jikl} = G^{klij}. \quad (9)$$

The inverse to H_{AB} is H^{AB} , and we define

$$G_{ijkl} = H^{AB} \mu_{Aij} \mu_{Bkl} \quad (10)$$

which has the same symmetries as (9). We require G^{ijkl} to be a tensor and use only the metric $g_{ij}(x)$ to define it. Then the ansatz

$$G^{ijkl} = z g^{i(k} g^{l)j} + \alpha g^{ij} g^{kl} \quad (11)$$

$$G_{ijkl} = v g_{i(k} g_{l)j} + \beta g_{ij} g_{kl} \quad (12)$$

where v , z , α and β are constants, is the most general one to fulfil the symmetries (9). One should mention that also curvature-dependent constants could have been introduced. The requirement that H_{AB} is the inverse to H^{AB} leads via (8,10) to

$$G_{ijkl}G^{klmp} = \delta_i^{(m} \delta_j^{p)}. \quad (13)$$

The requirement that G^{ijkl} is a tensor can be justified as follows: Let a curve $y^A(t)$, $0 < t < 1$ in V be given, then its length is

$$\sigma = \int_0^1 \left(H_{AB} \frac{dy^A}{dt} \frac{dy^B}{dt} \right)^{1/2} dt$$

i.e., with (2) and (8)

$$\sigma = \int_0^1 \left(G^{ijkl} \frac{dg_{ij}}{dt} \frac{dg_{kl}}{dt} \right)^{1/2} dt. \quad (14)$$

A coordinate transformation in $M : x^i \rightarrow \epsilon x^i$ changes $g_{ij} \rightarrow \epsilon^{-2} g_{ij}$. We now require that σ shall not be changed by such a transformation. Then α and z are constant real numbers. Inserting (11,12) into (13) gives $v z = 1$, hence $z \neq 0$. By a constant rescaling we get

$$v = z = 1 \quad (15)$$

and then (11,12,13) yield

$$\alpha \neq \frac{-1}{n}, \quad \beta = \frac{-\alpha}{1 + \alpha n}. \quad (16)$$

So we have got a one-parameter set of metrics in V . Eq. (16) fulfils the following duality relation: with $f(\alpha) = -\alpha/(1 + \alpha n)$, $f(f(\alpha)) = \alpha$ holds for all $\alpha \neq -1/n$.

$$\begin{aligned} G^{ijkl} &= g^{i(k} g^{l)j} + \alpha g^{ij} g^{kl} \\ G_{ijkl} &= g_{i(k} g_{l)j} + \beta g_{ij} g_{kl}. \end{aligned} \quad (17)$$

It holds: For $\alpha = -1/n$, the metric H_{AB} is not invertible.

Indirect proof: G^{ijkl} depends continuously on α , so it must be the case with the inverse. But

$$\lim_{\alpha \rightarrow -1/n}$$

applied to G_{ijkl} gives no finite result. Contradiction.

4 Signature of the superspace metric

Let S be the signature of the superspace metric H_{AB} . S depends on α and s . For convenience we define

$$\Theta = 0, \quad (\alpha > -1/n) \quad 1, \quad (\alpha < -1/n). \quad (18)$$

From continuity reasons it follows that S is a function of Θ and s : $S = S(\Theta, s)$. If we transform $g_{ij} \rightarrow -g_{ij}$ i.e., $s \rightarrow n - s$, then H_{AB} is not changed, i.e.,

$$S(\Theta, s) = S(\Theta, n - s). \quad (19)$$

We transform g_{ij} to diagonal form as follows

$$g_{11} = g_{22} = \dots = g_{ss} = -1, \quad g_{ij} = \delta_{ij} \quad \text{otherwise}. \quad (20)$$

4.1 Signature for $\Theta = 0$

To calculate $S(0, s)$ we may put $\alpha = 0$ and get with (8,11,15)

$$H_{AB} = \mu_{Aij} \mu_{Bkl} g^{ik} g^{jl} \quad (21)$$

which is a diagonal matrix. It holds $H_{11} = \dots = H_{nn} = 1$ and the other diagonal components are ± 1 . A full estimate gives in agreement with (19)

$$S(0, s) = s(n - s). \quad (22)$$

4.2 Signature for $\Theta = 1$

To calculate $S(1, s)$ we may put $\alpha = -1$ and get

$$H_{AB} = \mu_{Aij} \mu_{Bkl} (g^{ik} g^{jl} - g^{ij} g^{kl}). \quad (23)$$

For $A \leq n < B$, $H_{AB} = 0$, i.e., the matrix H_{AB} is composed of two blocks. For $A, B \leq n$ we get

$$H_{AB} = 0 \quad \text{for} \quad A = B, \quad 1 \quad \text{for} \quad A \neq B$$

a matrix which has the $(n - 1)$ -fold eigenvalue 1 and the single eigenvalue $1 - n$. For $A, B > n$ we have the same result as for the case $\alpha = 0$, i.e., we get $S(1, s) = 1 + s(n - s)$.

4.3 Result

The signature of the superspace metric is

$$S = \Theta + s(n - s) . \quad (24)$$

5 SUPERCURVATURE

We use exactly the same formulae as for finite-dimensional Riemannian geometry to define Christoffel affinities Γ_{BC}^A and Riemann tensor R_{BCD}^A . Using (4) we write all equations with indices $i, j = 1, \dots, n$. Then each pair of co-variant indices i, j corresponds to one contravariant index A . The following formulae appear:

$$\frac{\partial g^{ij}}{\partial g_{km}} = -g^{i(k} g^{m)j} \quad (25)$$

$$\Gamma^{ijklmp} = -\frac{1}{2}g^{i(k} g^{l)(m} g^{p)j} - \alpha g^{ij} g^{k(m} g^{p)l} - \frac{1}{2}g^{j(k} g^{l)(m} g^{p)i} \quad (26)$$

and, surprisingly independent of α we get

$$\Gamma_{ij}^{klmp} = -\delta_{(i}^{(k} g^{l)(m} \delta_{j)}^{p)} . \quad (27)$$

Consequently, also Riemann- and Ricci tensor do not depend on α :

$$R_{rs}^{klmpij} = \frac{1}{2} \left(\delta_{(r}^{(k} g^{l)(m} g^{p)(i} \delta_{s)}^{j)} - \delta_{(r}^{(k} g^{l)(i} g^{j)(m} \delta_{s)}^{p)} \right) . \quad (28)$$

Summing over $r = m$ and $s = p$ we get

$$R^{kl ij} = \frac{1}{4} \left(g^{ij} g^{kl} - n g^{k(i} g^{j)l} \right) . \quad (29)$$

The Ricci tensor has one eigenvalue 0. Proof: It is not invertible because it is proportional to the metric for the degenerated case $\alpha = -1/n$, cf. sct. 3.

The co-contravariant Ricci tensor reads

$$R_{kl}^{ij} = G_{klmp} R^{mpij} = \frac{1}{4} \left(g^{ij} g_{kl} - n \delta_k^{(i} \delta_l^{j)} \right) , \quad (30)$$

and the curvature scalar is

$$R = -\frac{1}{8}n(n-1)(n+2). \quad (31)$$

The eigenvector to the eigenvalue 0 of the Ricci tensor is g_{ij} . All other eigenvalues equal $-n/4$, and the corresponding eigenvectors can be parametrized by the symmetric traceless metrics, i.e. the multiplicity of the eigenvalue $-n/4$ is $(n-1)(n+2)/2$.

6 SUPERDETERMINANT

We define the superdeterminant

$$H = \det H_{AB}. \quad (32)$$

H is a function of g , α and n which becomes zero for $\alpha = -1/n$, cf. sct. 3. We use eqs. (8) and (17) to look in more details for the explicit value of H . The formal calculation for $n = 1$ leads to

$$H = H_{11} = G^{1111} = g^{11}g^{11} + \alpha g^{11}g^{11} = (1 + \alpha)g^{-2}.$$

Multiplication of g_{ij} with ϵ gives $g \rightarrow \epsilon^n g$, $H_{AB} \rightarrow \epsilon^{-2} H_{AB}$ and $H \rightarrow \epsilon^{-n(n+1)} H$. So we get in an intermediate step

$$H = H_1 g^{-n-1} \quad (33)$$

where H_1 is the value of H for $g = 1$. H_1 depends on α and n only. To calculate H_1 we put $g_{ij} = \delta_{ij}$ and get via $H_{ij} = \delta_{ij} + \alpha$, $H_{Ai} = 0$ for $A > n$, and $H_{AB} = \delta_{AB}$ for $A, B > n$ finally

$$H_1 = 1 + \alpha n. \quad (34)$$

This is in agreement with the $n = 1$ -calculation.

7 GRAVITY

Now, we come to the main application: The action for gravity shall be expressed by the metric of superspace. We start from the metric

$$ds^2 = dt^2 - g_{ij} dx^i dx^j \quad (35)$$

$i, j = 1, \dots, n$ with positive definite g_{ij} and $x^0 = t$. We define the second fundamental form K_{ij} by

$$K_{ij} = \frac{1}{2} g_{ij,0} . \quad (36)$$

The Einstein action for (35) is

$$I = - \int {}^*R \frac{1}{2} \sqrt{g} d^{n+1}x \quad (37)$$

where $g = \det g_{ij}$ and *R is the $(n+1)$ -dimensional curvature scalar for (35). Indices at K_{ij} will be shifted with g_{ij} , and $K = K^i_i$. With (36) we get

$$(K\sqrt{g})_{,0} = (K_{,0} + K^2)\sqrt{g} . \quad (38)$$

This divergence can be added to the integrand of (37) without changing the field equations. It serves to cancel the term $K_{,0}$ of I . So we get

$$I = \int \frac{1}{2} (K^{ij} K_{ij} - K^2 + R) \sqrt{g} d^{n+1}x \quad (39)$$

where R is the n -dimensional curvature scalar for g_{ij} . We make now the ansatz for the kinetic energy

$$W = \frac{1}{2} G^{ijmp} K_{ij} K_{mp} = \frac{1}{2} (K^{ij} K_{ij} + \alpha K^2) . \quad (40)$$

Comparing (40) with (39) we see that for $\alpha = -1$ (surprisingly, this value does not depend on n)

$$I = \int \left(W + \frac{R}{2} \right) \sqrt{g} d^{n+1}x \quad (41)$$

holds. Because of $n \geq 2$ this value α gives a regular superspace metric. (For $n = 1$, eq. (37) is a divergence, and $\alpha = -1$ gives not an invertible superspace-metric.)

Using the μ^{Aij} and the notations $z^A = \mu^{Aij} g_{ij} / 2$ and $v^A = dz^A/dt$ we get from (40,41)

$$I = \int \frac{1}{2} \left(H_{AB} v^A v^B + R(z^A) \right) \sqrt{g} d^{n+1}x \quad (42)$$

i.e., the action has the classical form of kinetic plus potential energy. The signature of the metric H_{AB} is $S = 1$. This can be seen from eqs. (18,24).

8 CONCLUSION

In eq. (42), Einstein gravity is given in a form to allow canonical quantization: The momentum v^A is replaced by $-i\partial/\partial z^A$ ($\hbar = 1$), and then the Wheeler - DeWitt equation for the world function $\psi(z^A)$ appears as Hamiltonian constraint in form of a wave equation:

$$\left(\square - R(z^A) \right) \psi = 0. \quad (43)$$

After early attempts in [1], the Wheeler - DeWitt equation has often been discussed, especially for cosmology, see e.g. [2-5]. Besides curvature, matter fields can be inserted as potential, too. It is remarkable that exactly for Lorentz and for Euclidean signatures in (35) (positive and negative definite g_{ij} resp.) the usual D'Alembert operator ($S = 1$) in (43) appears. For other signatures in (35), (43) has at least two timelike axes.

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